

Fig. 1

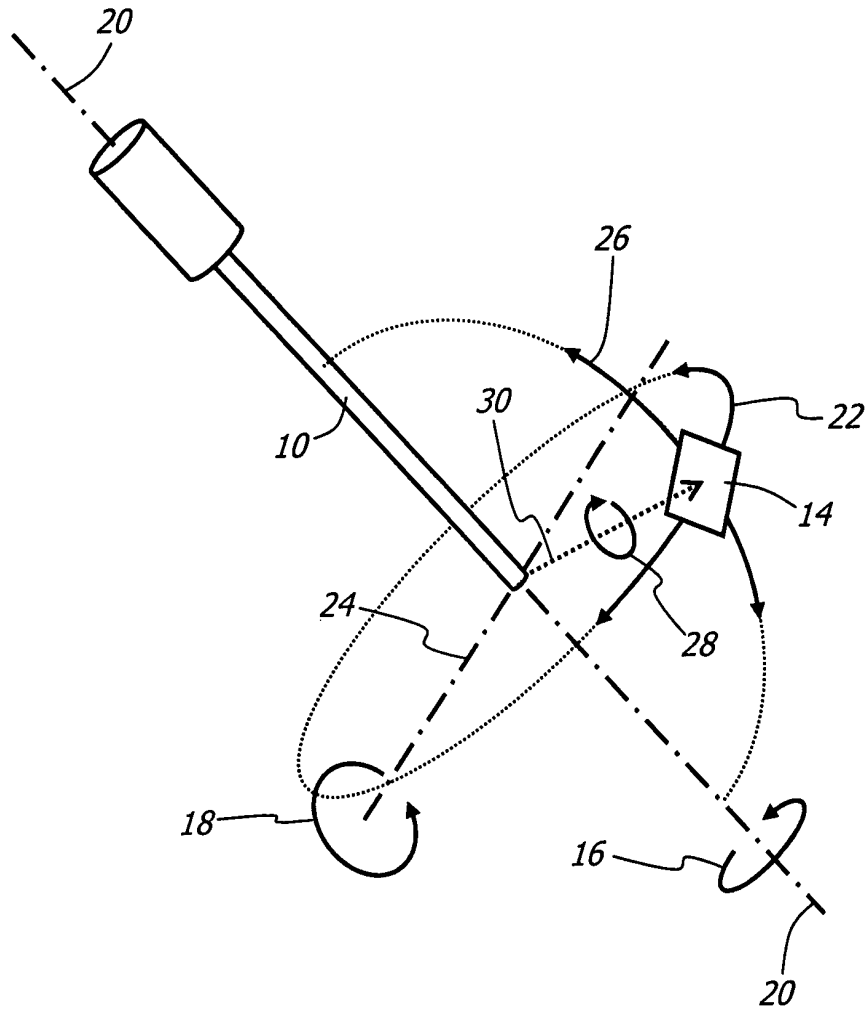
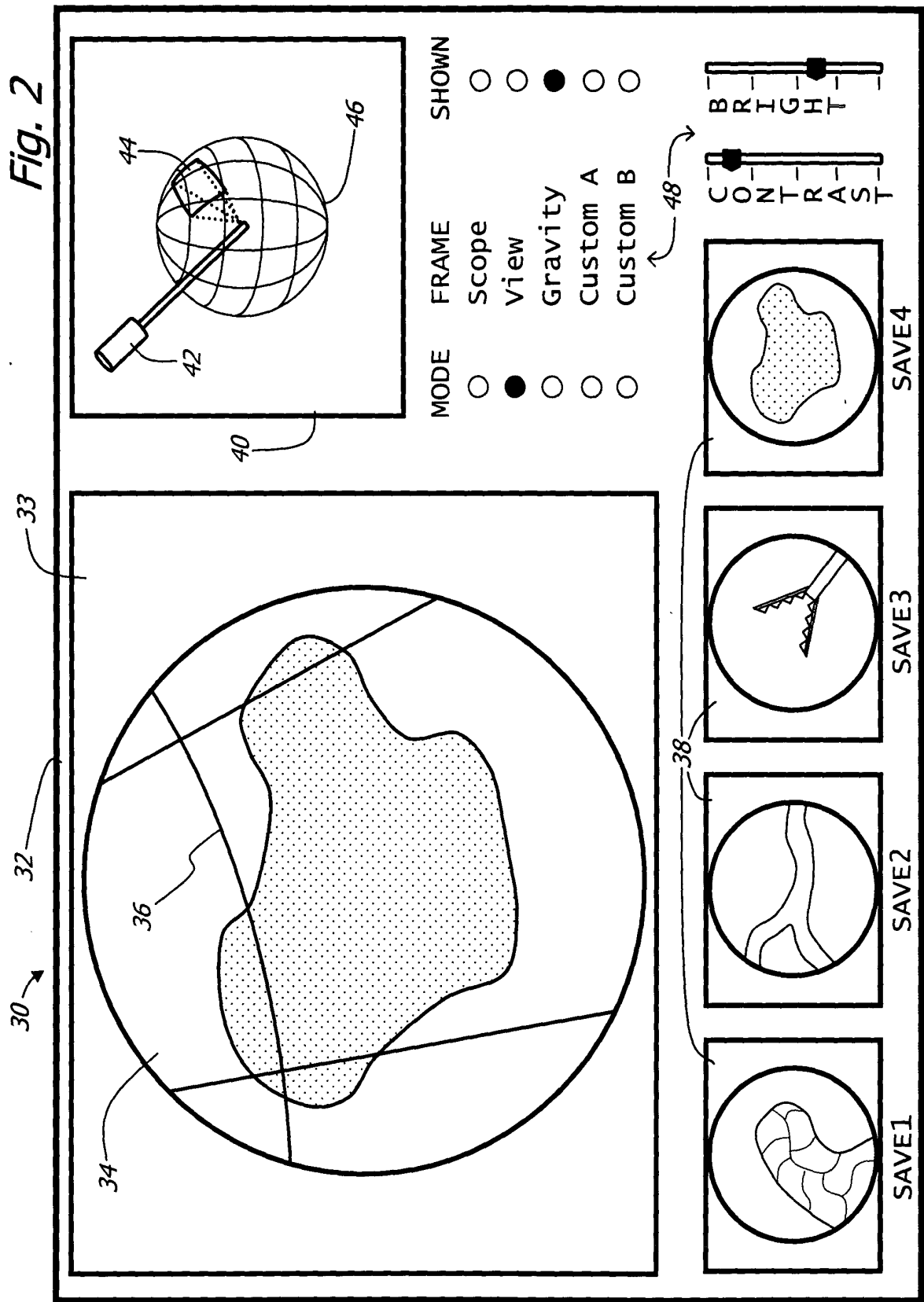


Fig. 2



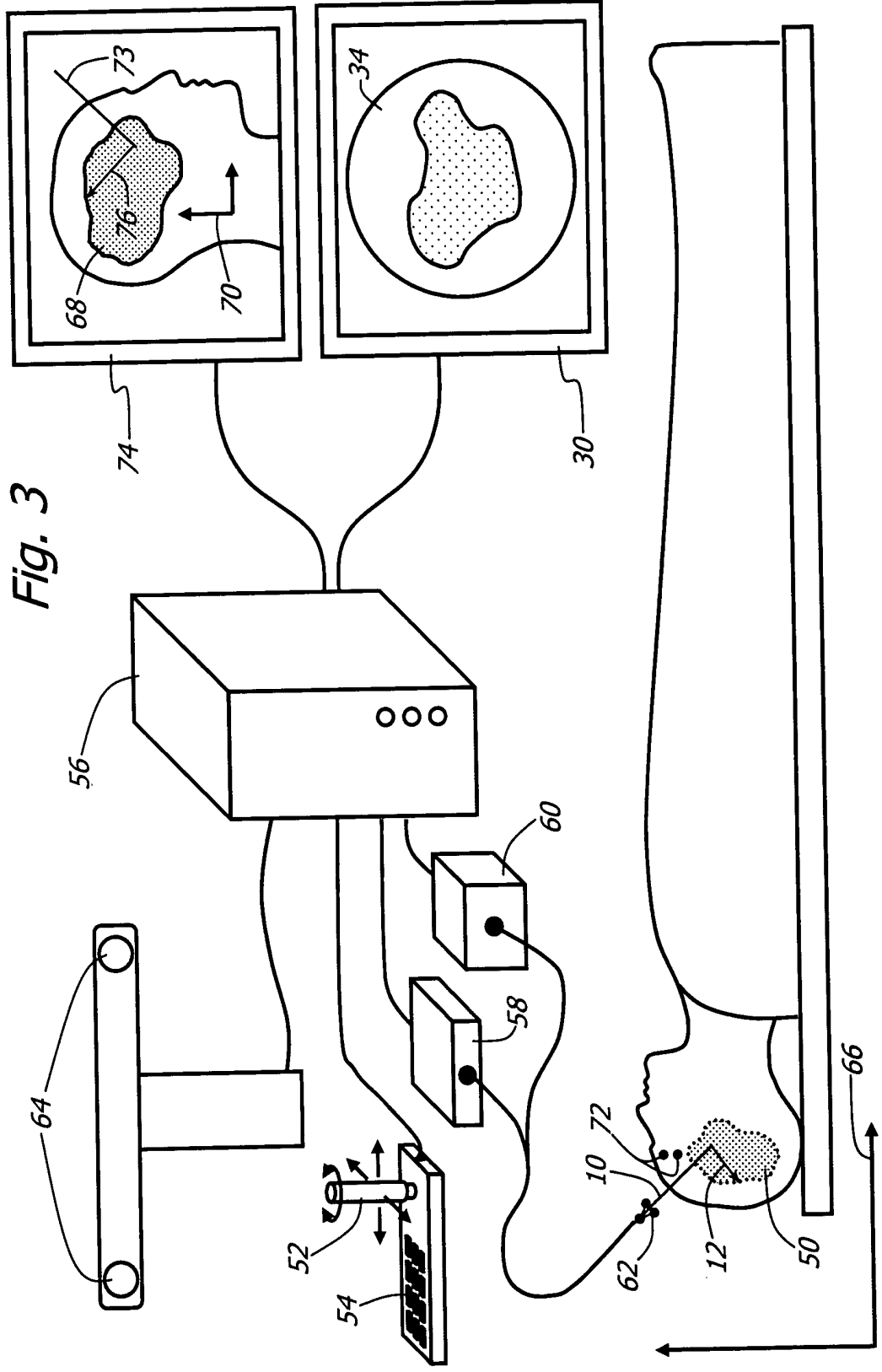


Fig. 3

Fig. 4A

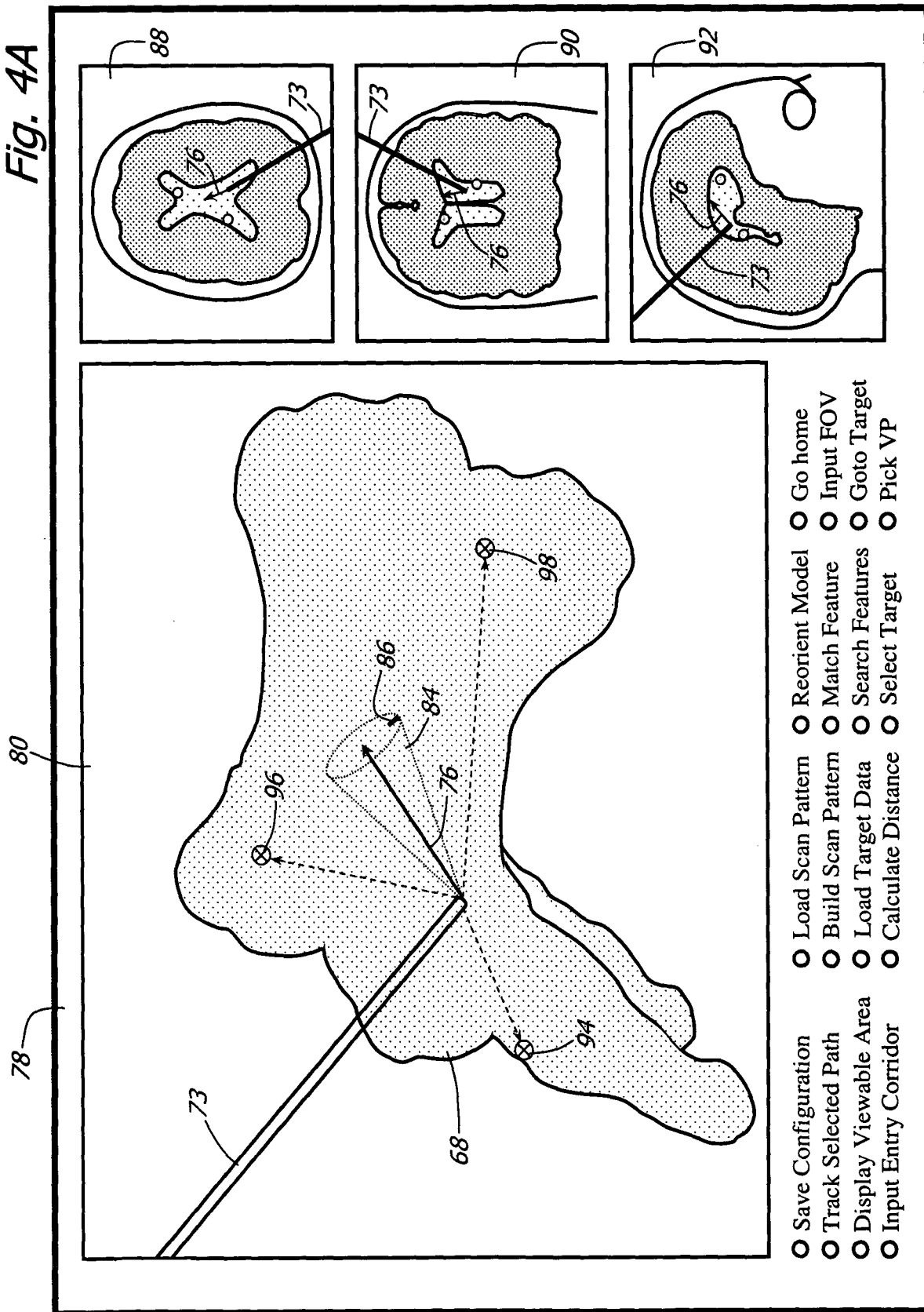
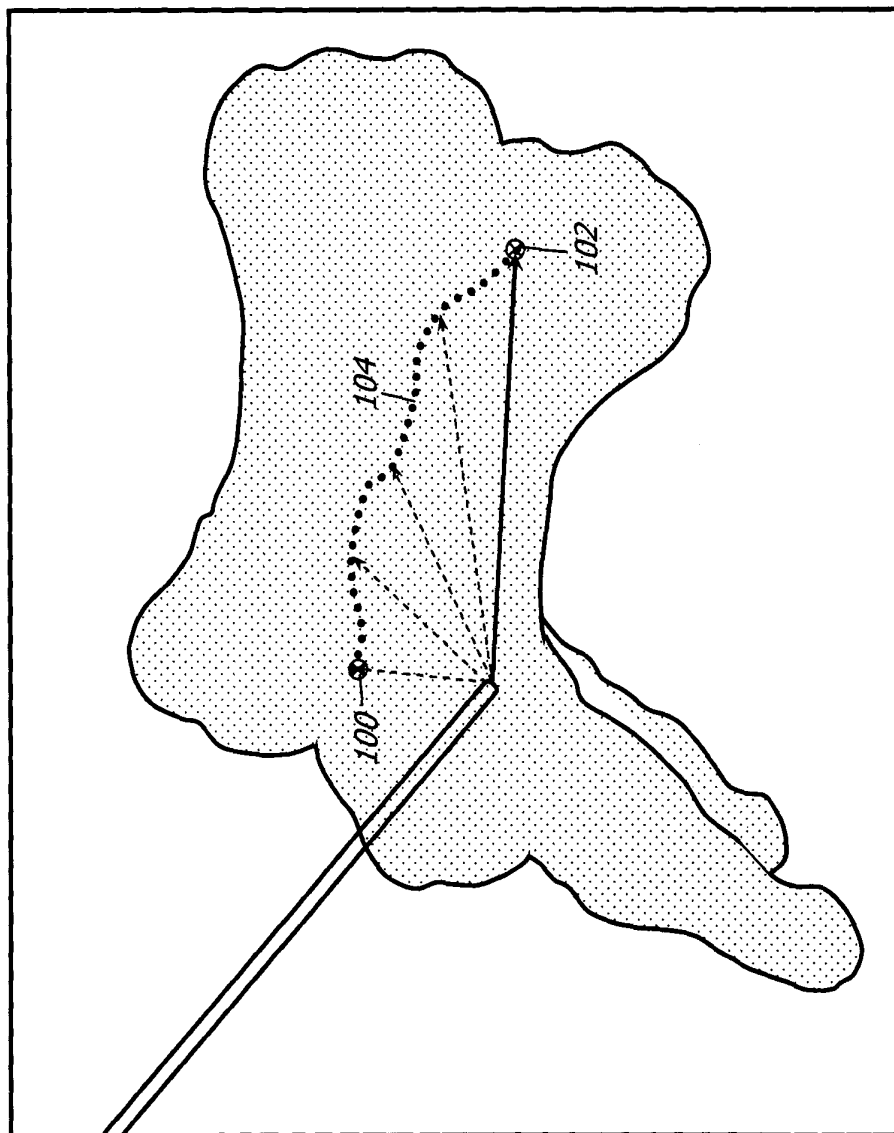
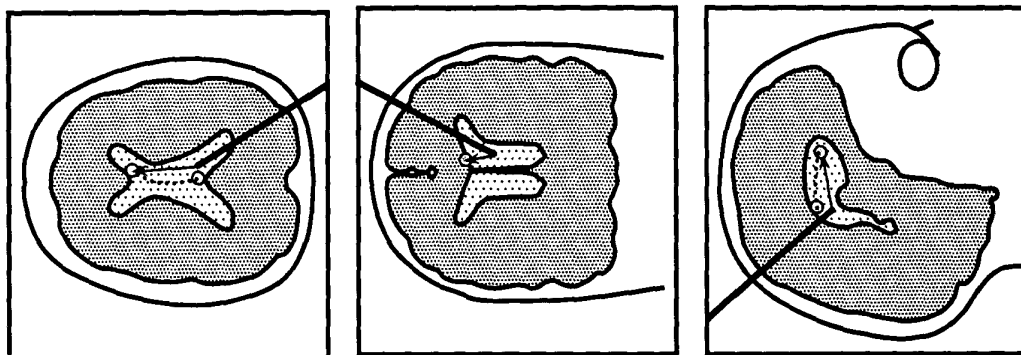


Fig. 4B



- Save Configuration
- Track Selected Path
- Display Viewable Area
- Input Entry Corridor
- Load Scan Pattern
- Build Scan Pattern
- Load Target Data
- Calculate Distance
- Reorient Model
- Match Feature
- Search Features
- Select Target
- Go home
- Input FOV
- Goto Target
- Pick VP

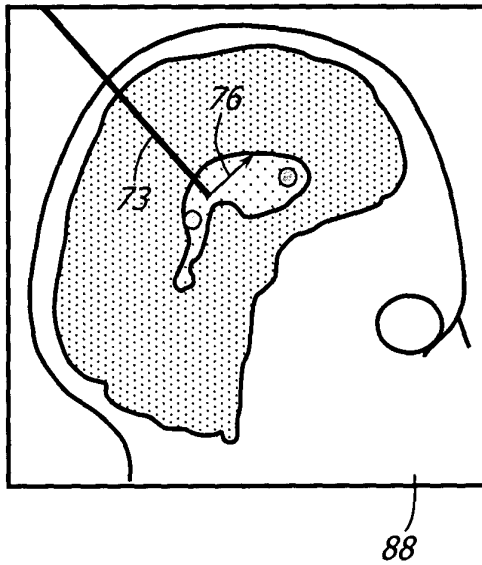


Fig. 5A

Fig. 5B

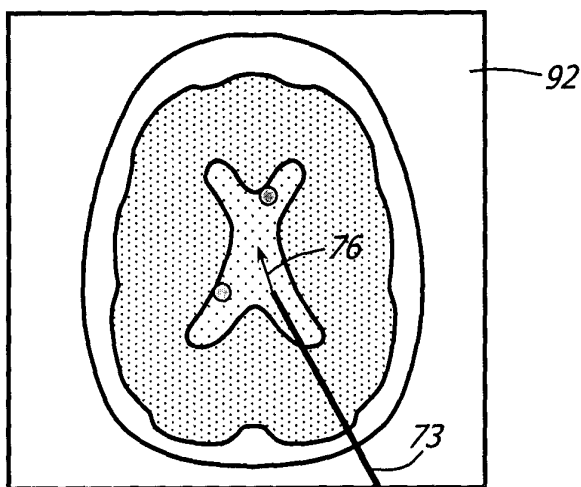
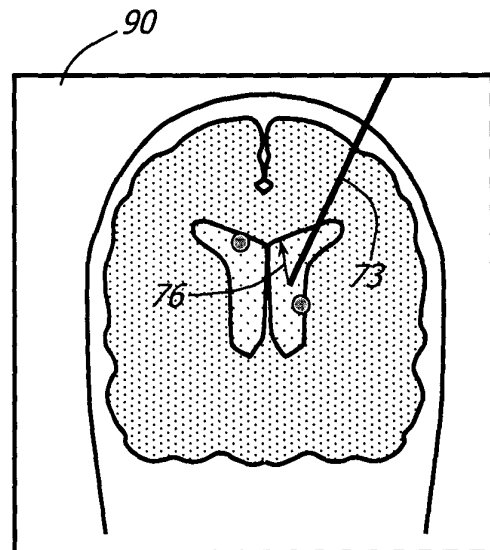


Fig. 5C

Fig. 6

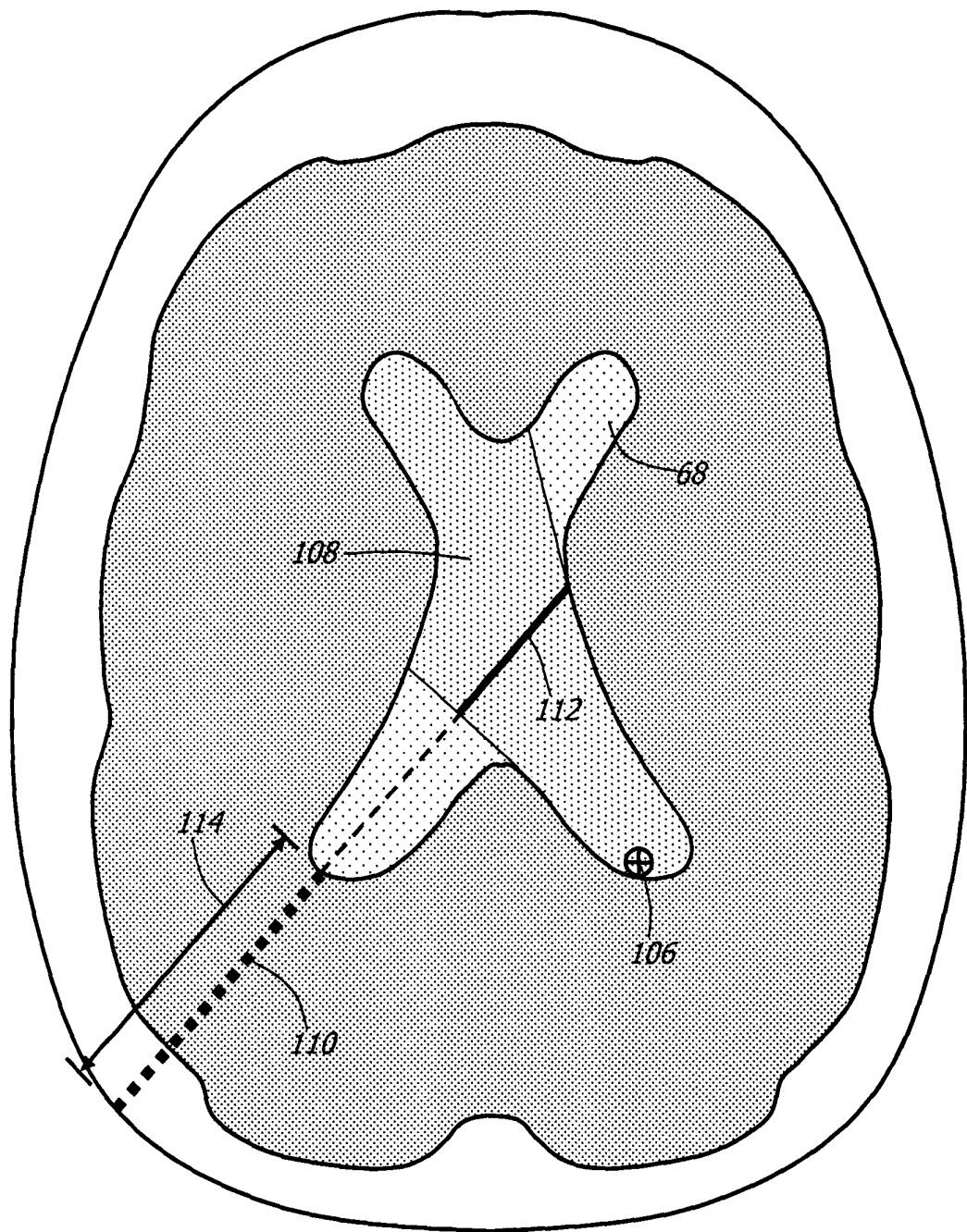
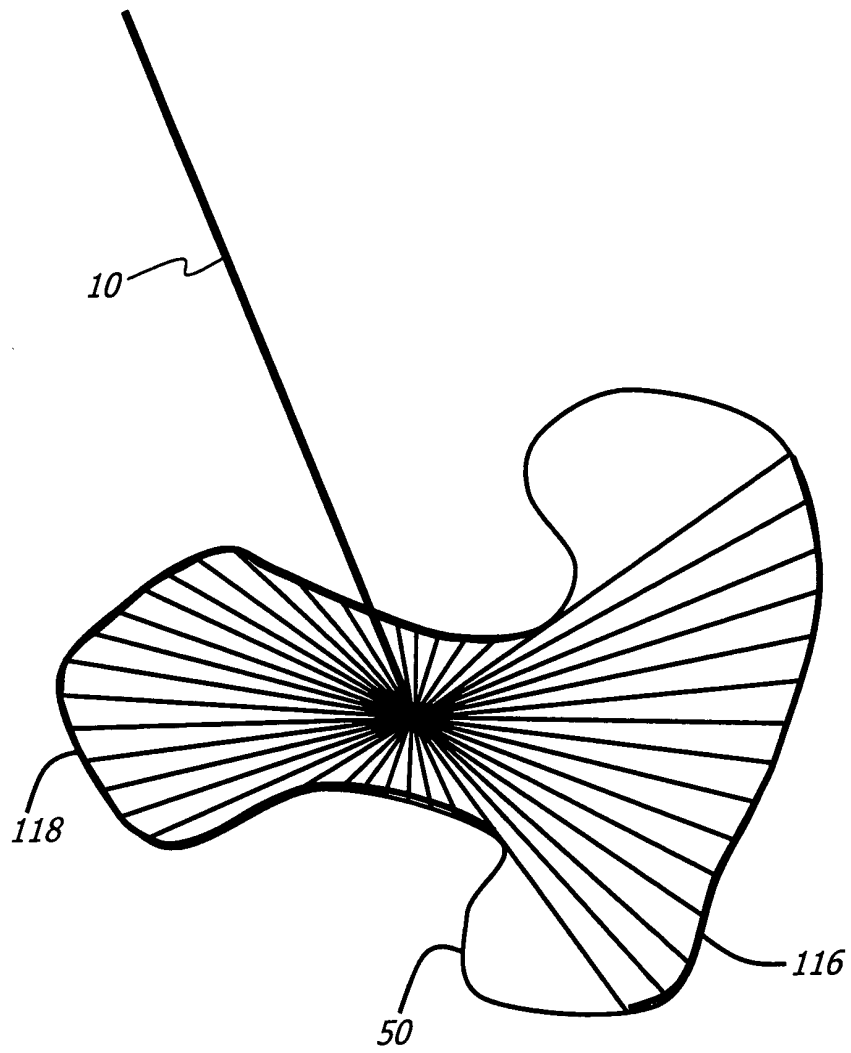


Fig. 7



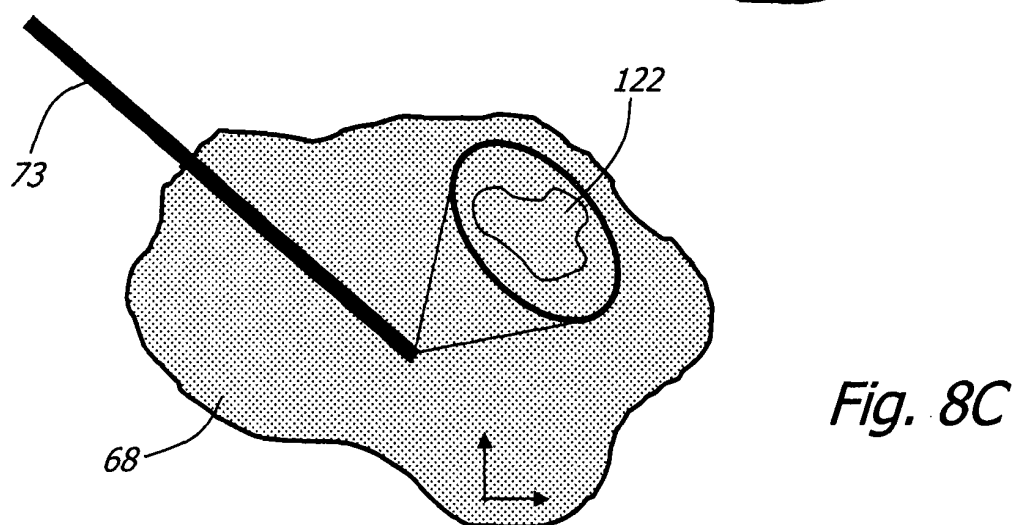
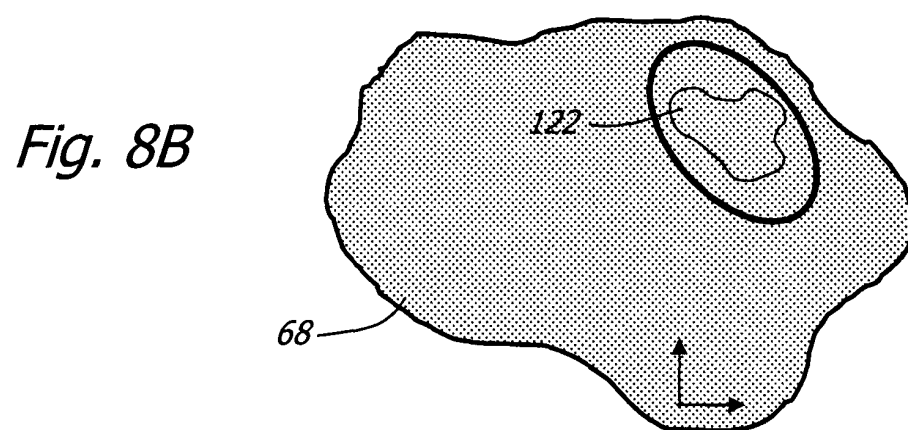
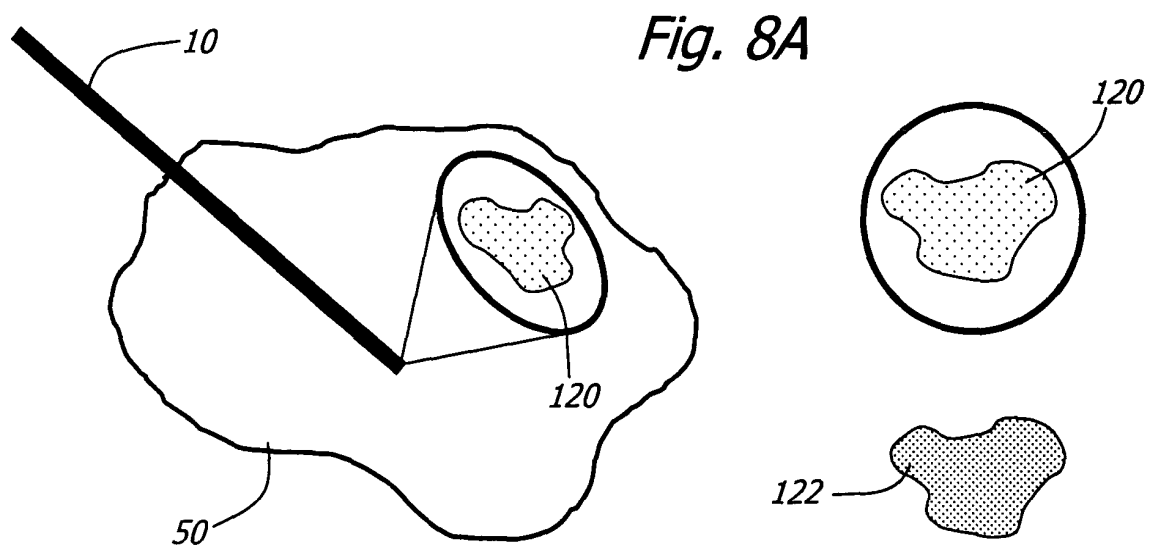


Fig. 8D

